

Learning, Confidence, and Business Cycles

Cosmin Ilut Hikaru Saijo

Duke & NBER UC Santa Cruz

CIGS Conference on Macroeconomic Theory and Policy
May 2016

Parsimonious mechanism for business cycle dynamics

- Propose: **Endogenous idiosyncratic uncertainty**
 - ▶ firms learn about own profitability prospects
- Behaves *as if* linear RBC model with endogenously determined
 - 1 Countercyclical labor wedge and spreads (from excess returns)
 - 2 Co-movement from demand shocks
 - 3 Amplification, propagation and hump-shaped dynamics

Parsimonious mechanism for business cycle dynamics

- Propose: **Endogenous idiosyncratic uncertainty**
 - ▶ firms learn about own profitability prospects
- Do not require additional shocks or rigidities such as
 - 1 Wedge shocks (countercyclical labor wedge and spreads)
 - 2 Nominal rigidities (co-movement)
 - 3 Habit, adjustment cost (internal propagation)

Countercyclical endogenous idiosyncratic uncertainty

Firms face Knightian uncertainty about own profitability

- ① Learning through production: **lower scale** → **more uncertainty**
- ② Uncertainty affects input choice: **more uncertainty** → **lower scale**

Feedback arises from **any** shock that moves activity

Countercyclical idiosyncratic uncertainty shows up

- As **countercyclical wedges**: labor and asset prices move 'too much' compared to what econometrician measures
 - ▶ rationalize 'excess volatility'
- In linear decision rules at firm level
- In the cross-sectional average through aggregation

Model: Preferences

Representative household: recursive multiple priors utility

$$U_t(C; s^t) = \ln C_t - \varphi \frac{H_t^{1+\eta}}{1+\eta} + \beta \min_{p \in \mathcal{P}_t(s^t)} E^p[U_{t+1}(C; s^t, s_{t+1})]$$

- $\mathcal{P}_t(s^t)$: one-stead-ahead set of probability distributions
- Larger set $\mathcal{P}_t(s^t) \rightarrow$ less confidence

Production

- Firms: continuum, indexed by $l \in [0, 1]$, perfectly competitive

$$Y_{l,t} = A_t \{ z_{l,t} K_{l,t-1}^\alpha H_{l,t}^{1-\alpha} + \nu_{l,t} \}$$

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- Aggregate TFP shock

$$\ln A_t = \rho_A \ln A_{t-1} + \epsilon_{A,t}, \quad \epsilon_{A,t} \sim N(0, \sigma_A^2)$$

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- Idiosyncratic TFP shock

$$z_{l,t} = (1 - \rho_z) \bar{z} + \rho_z z_{l,t-1} + \epsilon_{z,l,t}, \quad \epsilon_{z,l,t} \sim N(0, \sigma_z^2)$$

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- Idiosyncratic additive shock, $\nu_{l,t} \sim N(0, \sigma_\nu^2)$

Information

$$Y_{l,t} = A_t \{ z_{l,t} K_{l,t-1}^\alpha H_{l,t}^{1-\alpha} + \nu_{l,t} \}$$

- $z_{l,t}$ and $\nu_{l,t}$ unobservable to agents \rightarrow learning
- Non-invertibility problem: path of output and input not fully revealing about the unobservable shocks
- Interpretations of additive shock
 - 1 Aggregation of production units with common and idiosyncratic shocks
 - 2 Sale is signal on unobservable persistent demand shock

Heterogeneous-firm RBC model

- Firms: choose $\{K_{l,t}, H_{l,t}, I_{l,t}\}$ to maximize

$$E_0^* \sum_{t=0}^{\infty} M_0^t D_{l,t}$$

- ▶ M_0^t : prices of contingent claims, under **worst case probabilities**

$$D_{l,t} = Y_{l,t} - W_t H_{l,t} - I_{l,t}$$

- Resource constraint:

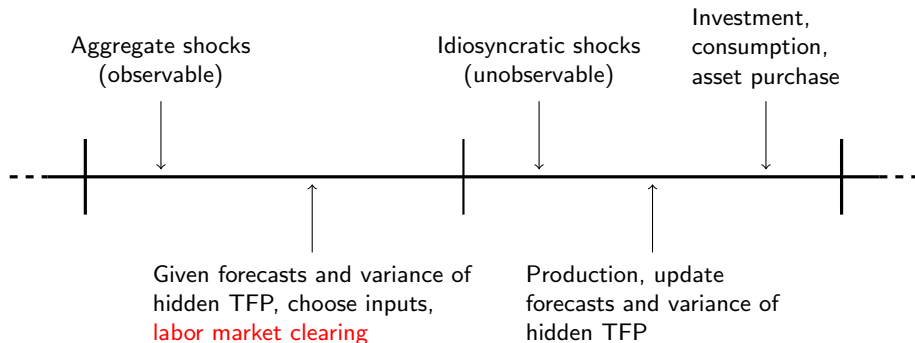
$$Y_t = C_t + I_t + G_t$$

$$\ln G_t = (1 - \rho_g)G + \rho_g \ln G_{t-1} + \epsilon_{g,t}, \quad \epsilon_{g,t} \sim N(0, \sigma_g^2)$$

Timeline of events within a period

Stage 1

Stage 2



Learning and ambiguity about idiosyncratic productivity

- Estimate $z_{l,t}$ from observables: linear + Gaussian \rightarrow Kalman filter

$$\text{Observation : } Y_{l,t}/A_t = K_{l,t-1}^\alpha H_{l,t}^{1-\alpha} z_{l,t} + \nu_{l,t}$$

$$\text{Transition : } z_{l,t} = (1 - \rho_z)\bar{z} + \rho_z z_{l,t-1} + \epsilon_{z,l,t}$$

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- Not confident in the Kalman filter estimate: **set** of distributions

$$E_t z_{l,t+1} = (1 - \rho_z)\bar{z} + \rho_z \tilde{z}_{l,t|t} + \mu_{l,t}; \quad \mu_{l,t} \in [-a_{l,t}, a_{l,t}]$$

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- Confidence lower when estimation uncertainty is higher

$$-a_{l,t} = -\eta_a \sqrt{\Sigma_{l,t|t}}$$

- ▶ Distributions “close” to filter estimate (relative entropy distance)

Ambiguity and the law of large numbers

- Each firm's expected $z_{l,t+1}$ under **worst-case probability**

$$E_t^* z_{l,t+1} = (1 - \rho_z) \bar{z} + \rho_z \tilde{z}_{l,t|t} \underbrace{- a_{l,t}}_{=-\eta_a \sqrt{\Sigma_{l,t|t}}}$$

- ▶ Household acts **as if** conditional mean of each $z_{l,t+1}$ is lower
- ▶ First-order effect of uncertainty

- **Cross-sectional average given by a set**

$$\left[\bar{z} - \int a_{l,t} dl, \bar{z} + \int a_{l,t} dl \right]$$

- ▶ Epstein & Schneider (2003): formal treatment of LLN with ambiguity

Linearized solution

- ① Filtering problem is linear \rightarrow analytic law of motion for $\Sigma_{l,t|t}$
 - ▶ Inputs have first-order effect on the level of posterior variance
- ② First-order feedback from uncertainty to decision rules through $-a_{l,t}$
- ③ In turn, linear decision rules \rightarrow easy aggregation
 - ▶ Cross-sectional mean: sufficient statistic for tracking distributions

Implication: comovement and countercyclical labor wedge

- Standard model

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- Our model: labor chosen under worst case expectation

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→ choose H as if productivity low → H low

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- Labor wedge: implicitly define labor tax

$$\varphi H_t^\eta = (1 - \tau_t) \lambda_t MPL_t \quad \Rightarrow \quad \frac{E_t^*[\lambda_t MPL_t]}{\lambda_t MPL_t} = 1 - \tau_t$$

Low confidence → econometrician rationalizes 'surprisingly low' H by high labor tax

Implication: countercyclical ex-post excess return

- Euler conditions for capital and risk-free assets

$$\lambda_t = \beta E_t^*[\lambda_{t+1} R_{t+1}^K]$$

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→ under linearization, $E_t^* R_{t+1}^K - R_t = 0$

- Pricing based on worst case \neq econometrician's DGP
- During low confidence times, demand for capital 'surprisingly low'
→ ex-post excess return $R_{t+1}^K - R_t$ high
- Implication extends to defaultable corporate bonds
→ countercyclical excess bond premia (Gilchrist & Zakrajsek 2012)

Calibration

Magnitude of feedback loop determined by

① Variability of inputs

- ▶ Inverse Frisch elasticity $\eta = 0$
- ▶ Capital utilization

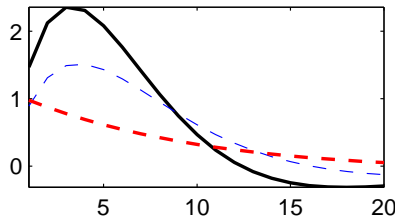
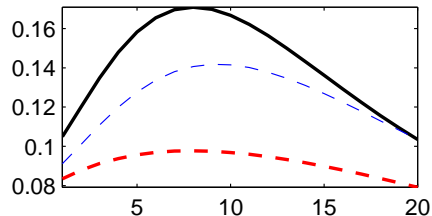
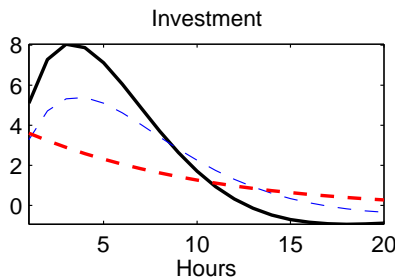
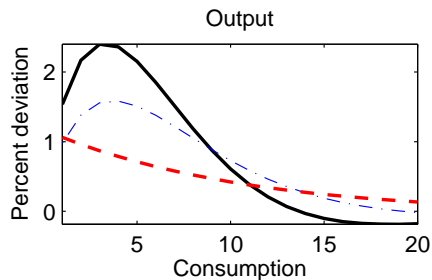
② Size and variability of posterior variance

- ▶ Idiosyncratic TFP shock $\rho_z = 0.5, \sigma_z = 0.4$
 - ★ establishment-level data (Bloom et al. 2014, Kehrig 2015)
- ▶ SS posterior variance $\Sigma = 0.1$
 - ★ estimated posterior variance of firm-specific shocks (David et al. 2015)

③ Size of entropy constraint

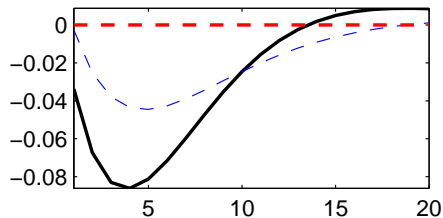
- ▶ Reasonable theoretical upper bound $\eta_a = 2$ (Ilut & Schneider 2014)
- ▶ Empirical: firm-level capital return forecasts across analysts
 - ★ Set $\eta_a = 0.4$ to get average dispersion of 39% (vs 43% in Senga 2014)

IRF to aggregate TFP shock

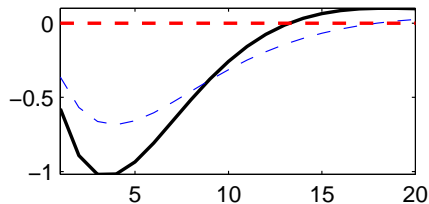


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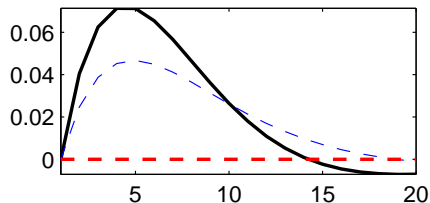
Labor wedge



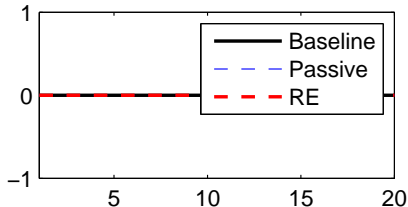
Ex-post excess return



Cross-sectional mean of worst-case TFP

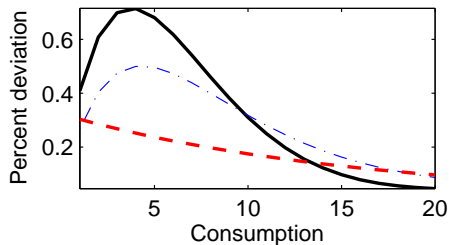


Cross-sectional mean of realized TFP

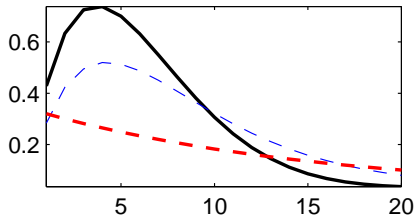
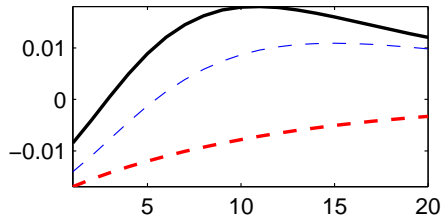
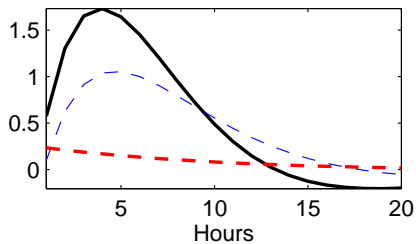


IRF to government spending shock

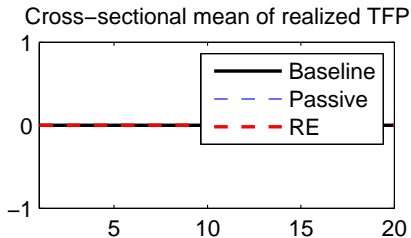
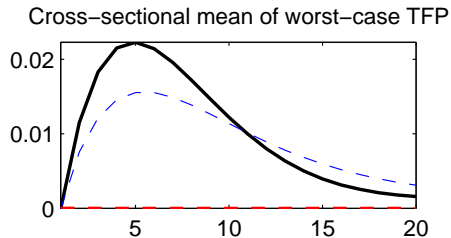
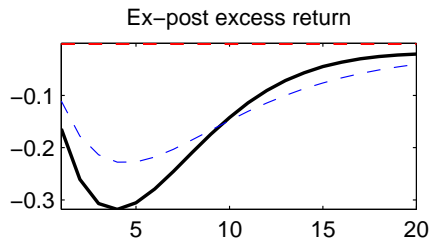
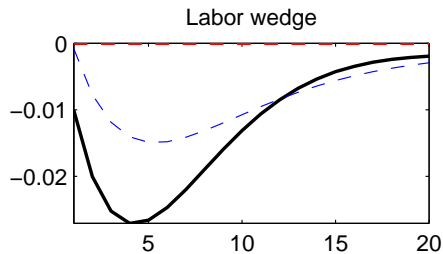
Output



Investment



IRF to government spending shock



Bayesian estimation on US aggregate data

- Linearization \Rightarrow estimation using standard Kalman filter
- Quantitative model with additional rigidities (CEE, 2005)
 - ▶ real: habit formation, investment adjustment costs
 - ▶ nominal: sticky prices and wages
- Shocks: TFP, G, mon. policy and 'financial wedge' shock

$$\Delta_t^k \simeq E_t^* R_{t+1}^k - R_t$$

- US Data: $Y_t, H_t, I_t, C_t, \pi_t, R_t, Spread_t$ (on BAA corporate bond)

$$\begin{aligned} Spread_t &\equiv R_t^k - R_{t-1} \\ &= \underbrace{\left(E_{t-1}^* R_t^k - R_{t-1} \right)}_{\text{wedge shock}} + \underbrace{\left(R_t^k - E_{t-1}^* R_t^k \right)}_{\text{endogenous uncertainty}} \end{aligned}$$

- ▶ estimate both flex and sticky price versions
- ▶ stochastic singularity \Rightarrow iid measurement error

Results

- ① Endogenous uncertainty: parsimonious friction \Rightarrow reduce other rigidities

Model	η_a	Pr(price Δ)	Pr(wage Δ)	Inv. adj. cost	Habit
RE	0	0.24	0.04	0.3	0.62
Baseline	1.3	0.44	0.98	0.06	0.47

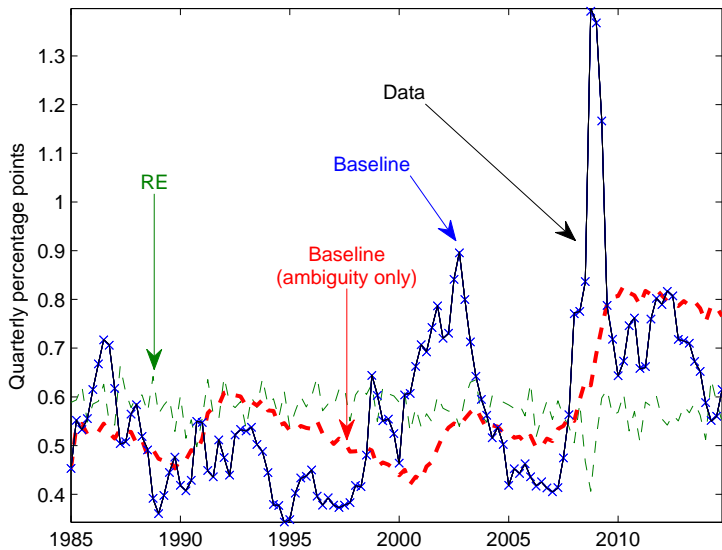
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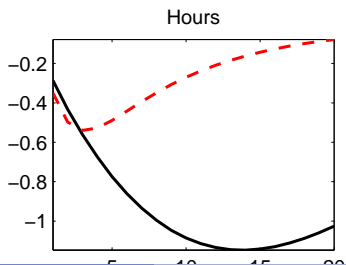
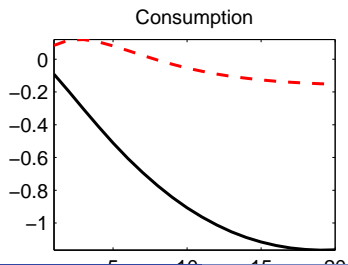
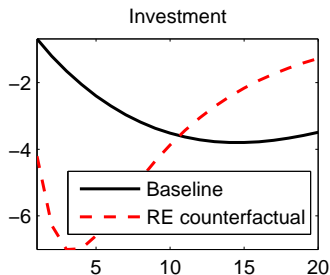
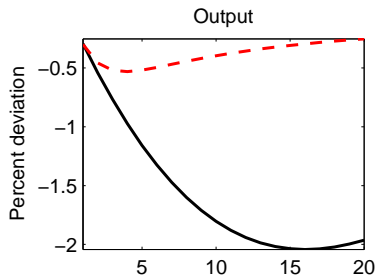
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- 2 Endogenous uncertainty model fits data better
 - ▶ marginal data density is higher (both flex and sticky price versions)
 - ▶ under RE: observed spread is mostly just measurement error
 - ▶ but well fitted under model with endogenous uncertainty

Spread: data vs. models



Endogenous uncertainty: countercyclical spread \Rightarrow bus. cycle comovement



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- 3 Variance decomposition: financial shock more important with learning

Model (sticky price)	Y	H	I	C	π	R
RE	0.15	0.23	0.12	0.22	0.88	0.90
Baseline	0.73	0.81	0.76	0.61	0.88	0.84

Policy implication of endogenous uncertainty

- Endogenous uncertainty \Rightarrow Policy matters
- Policy experiment:
 - ▶ modify Taylor rule to include adjustment to credit spread ϕ_{spread}
 - ▶ lower output growth variation: **from stabilizing endogenous uncertainty**

ϕ_{spread}	Std. of output growth	
	Baseline	Fixed uncertainty
0	0.60	0.60
-0.5	0.59	0.60
-1.0	0.57	0.60
-1.5	0.52	0.63

Conclusion

- Heterogeneous-firm business cycle model where firms face Knightian uncertainty about their own profitability
- Feedback loop between uncertainty and economic activity produces
 - ▶ Countercyclical labor wedge and ex-post excess return on capital
 - ▶ Co-movement in response to non-TFP shocks
 - ▶ Strong internal propagation with amplified and hump-shaped dynamics
- Estimation: inference on rigidities and shocks
- Policy implications

Interpreting the additive shock ($\nu_{l,t}$)

- 1 At the aggregate level, observationally equivalent to model where firms face unobservable demand shock
 - ▶ Each unit of good l : provides sum of good specific and idiosyncratic quality

$$\tilde{Y}_{l,t} = \sum_{j=1}^{Y_{l,t}} (z_{l,t} + \tilde{v}_{l,j,t})$$

- ▶ where units produced $Y_{l,t} = K_{l,t-1}^\alpha H_{l,t}^{1-\alpha}$
- ▶ Noisy signal about persistent quality $z_{l,t}$: procyclical precision

$$\tilde{Y}_{l,t}/Y_{l,t} = z_{l,t} + \nu_{l,t}, \quad \nu_{l,t} \sim N\left(0, \frac{\sigma_{\tilde{v}}^2}{Y_{l,t}}\right)$$

- ▶ demand is a function of estimate of quality $z_{l,t}$
- 2 Aggregation of production units with common and idio shocks

▶ Return

Kalman filter

- Estimate

$$\tilde{z}_{l,t|t} = \tilde{z}_{l,t|t-1} + \text{Gain}_{l,t}(Y_{l,t}/A_t - \tilde{z}_{l,t|t-1}F_{l,t})$$

- Kalman gain

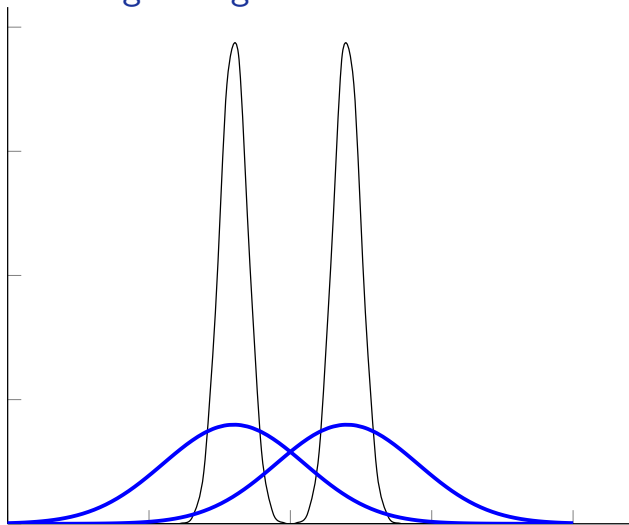
$$\text{Gain}_{l,t} = \left[\frac{F_{l,t}^2 \Sigma_{l,t|t-1}}{F_{l,t}^2 \Sigma_{l,t|t-1} + \sigma_{\nu,t}^2} \right] F_{l,t}^{-1}$$

- Mean square error

$$\begin{aligned} \Sigma_{l,t|t} &= (1 - \text{Gain}_{l,t}F_{l,t})\Sigma_{l,t|t-1} \\ &= \frac{\sigma_{\nu,t}^2 \Sigma_{l,t|t-1}}{F_{l,t}^2 \Sigma_{l,t|t-1} + \sigma_{\nu,t}^2} \end{aligned}$$

▶ Return

Illustration: distinguishing distributions



▶ Return

Relative entropy distance

Agents consider the conditional means $\mu_{l,t+1}^*$ that are sufficiently close to the long run average of zero in the sense of relative entropy:

$$\frac{(\mu_{l,t+1}^*)^2}{2\rho_z^2 \Sigma_{l,t|t}} \leq \frac{1}{2} \eta_a^2$$

- LHS: relative entropy between two normal distributions that share the same variance $\rho_z^2 \Sigma_{l,t|t}$ but have different means ($\mu_{l,t+1}^*$ and zero)

▶ Return

Linearized solution

- 1 Filtering problem is linear \rightarrow analytic law of motion for $\Sigma_{l,t|t}$
 - ▶ Inputs have first-order effect on the level of posterior variance

$$\hat{\Sigma}_{l,t-1|t-1} = \varepsilon_{\Sigma,\Sigma} \hat{\Sigma}_{l,t-2|t-2} - \varepsilon_{\Sigma,F} \hat{F}_{l,t-1}, \quad (1)$$

- 2 First-order feedback from uncertainty to decision rules through $-a_{l,t}$

$$E_t^* \hat{z}_{l,t} = \varepsilon_{z,z} \hat{z}_{l,t-1|t-1} - \varepsilon_{z,\Sigma} \hat{\Sigma}_{l,t-1|t-1}, \quad (2)$$

- 3 In turn, linear decision rules \rightarrow easy aggregation
 - ▶ Cross-sectional mean: sufficient statistic for tracking distributions

$$E_t^* \hat{z}_t = \underbrace{\varepsilon_{z,z} \hat{z}_{t-1|t-1}}_{=0} - \varepsilon_{z,\Sigma} \varepsilon_{\Sigma,\Sigma} \hat{\Sigma}_{t-2|t-2} + \varepsilon_{z,\Sigma} \varepsilon_{\Sigma,F} \hat{F}_{t-1} \quad (3)$$

where $\hat{x}_t \equiv \int \hat{x}_{l,t} dl$

Recursive competitive equilibrium

- Household's problem at stage 1 : *hats* RVs resolved at stage 2

$$V_1^h(\vec{\theta}_l, B; \xi_1, X) = \max_H \left\{ -\varphi \frac{H^{1+\eta}}{1+\eta} + E^*[V_2^h(\hat{m}; \hat{\xi}_2, X)] \right\} \quad (4)$$

s.t. $\hat{m} = WH + RB + \int (\hat{D}_l + \hat{P}_l)\theta_l dl - G$

- Household's problem at stage 2:

$$V_2^h(m; \xi_2, X) = \max_{C, \vec{\theta}'_l, B'} \left[\ln C + \beta \int V_1^h(\vec{\theta}'_l, B'; \xi'_1, X') dF(X'|X) \right]$$

s.t. $m \geq C + B' + \int P_l \theta'_l dl; \quad \xi'_1 = \Gamma(\xi_2, X)$ (5)

Recursive competitive equilibrium

- Firm l 's problem at stage 1

$$v_1^f(\tilde{z}_l, \Sigma_l, K_l; \xi_1, X) = \max_{H_l} E^*[v_2^f(\hat{z}'_l, \Sigma'_l, K_l; \hat{\xi}_2, X)] \quad (6)$$

s.t. Updating rules of Kalman filter

- Firm l 's problem at stage 2: $v_2^f(\tilde{z}'_l, \Sigma'_l, K_l; \xi_2, X)$ equals

$$\max_{I_l} \left[\lambda(Y_l - WH_l - I_l) + \beta \int v_1^f(\tilde{z}'_l, \Sigma'_l, K_l; \xi'_1, X') dF(X'|X) \right]$$

s.t. $K'_l = (1 - \delta)K_l + I_l$; $\xi'_1 = \Gamma(\xi_2, X)$ (7)

▶ Return

Parameters

γ	Labor augmenting tech growth	1.004
α	Capital share	0.3
β	Discount factor	0.99
η	Inverse Frisch elasticity	0
δ_0	SS depreciation	0.025
δ_2/δ_1	Convexity of depreciation	0.15
η_a	Size of entropy constraint	0.4
$\bar{\Sigma}$	SS posterior variance	0.1
	(Kalman gain)	0.47
\bar{g}	SS share of gov spending	0.2
ρ_z	Idiosyncratic TFP	0.5
σ_z	Idiosyncratic TFP	0.4
ρ_A	Aggregate TFP	0.95
ρ_g	Government spending	0.95
ρ_σ	Firm-level dispersion	0.85

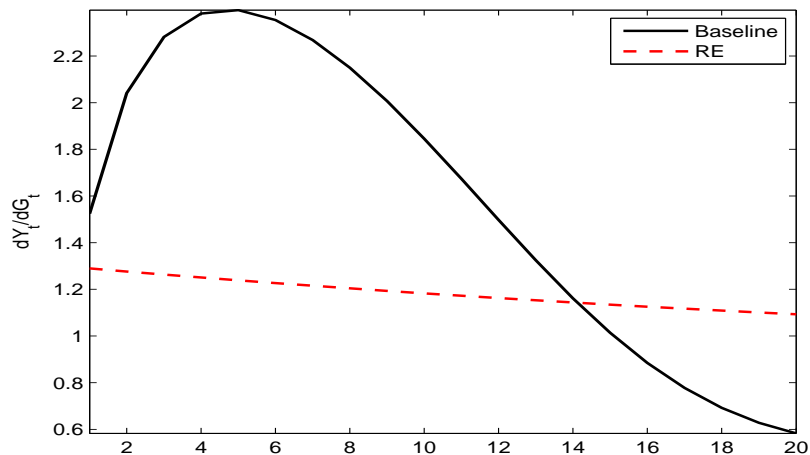
▶ Return

HP-filtered moments (TFP shock only)

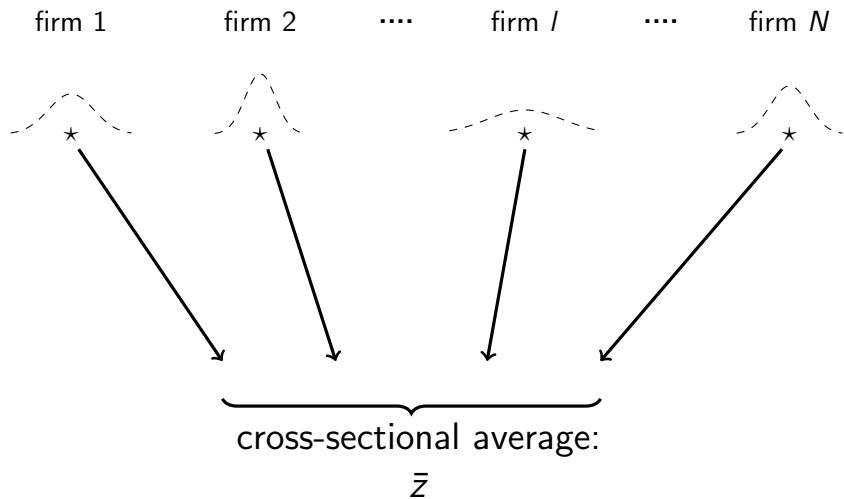
	Data	Our model	RE
$\sigma(y)$	1.11	1.11	0.49
$\sigma(c)/\sigma(y)$	0.72	0.11	0.17
$\sigma(i)/\sigma(y)$	3.57	2.95	3.23
$\sigma(h)/\sigma(y)$	1.64	1.02	0.86
$\sigma(c, y)$	0.86	0.72	0.85
$\sigma(i, y)$	0.92	0.99	0.99
$\sigma(h, y)$	0.88	0.99	0.99
$\sigma(y, \tau_I)$	-0.83	-0.95	0
$\sigma(h, \tau_I)$	-0.97	-0.95	0
$\sigma(y_t, y_{t-1})$	0.89	0.87	0.66
$\sigma(h_t, h_{t-1})$	0.95	0.88	0.66
$\sigma(\Delta y_t, \Delta y_{t-1})$	0.39	0.44	-0.06
$\sigma(\Delta h_t, \Delta h_{t-1})$	0.71	0.52	-0.06

Note: We choose the st. dev of aggregate TFP shock so that the output st. dev in the model matches the data.

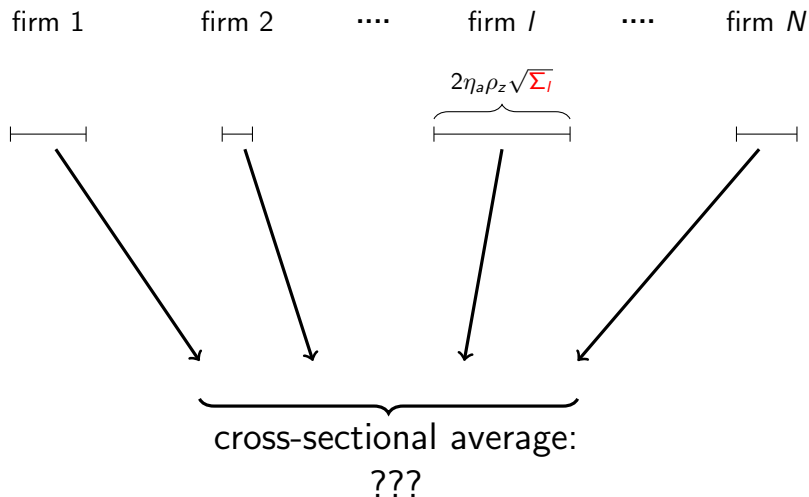
Government spending multiplier



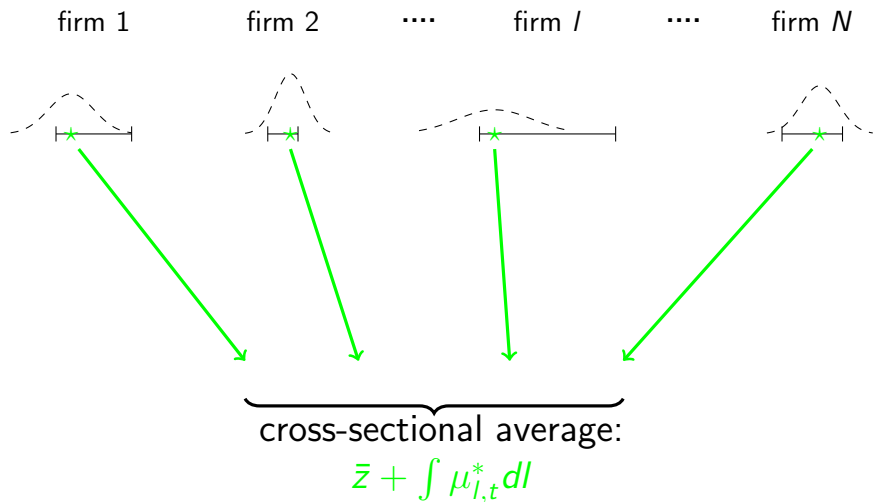
Law of large numbers for risky random variables



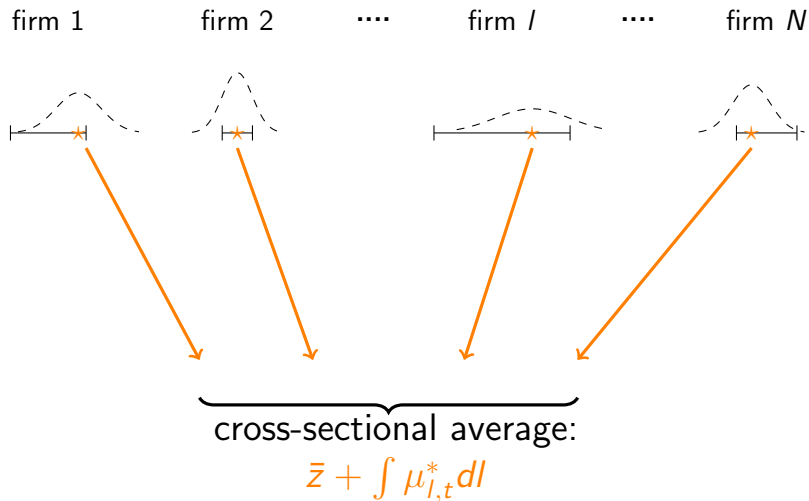
Law of large numbers for ambiguous random variables



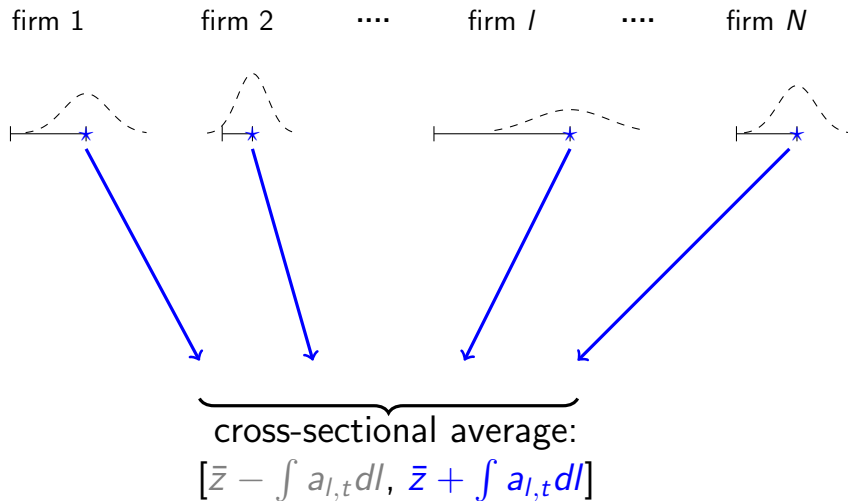
Law of large numbers for ambiguous random variables



Law of large numbers for ambiguous random variables



Law of large numbers for ambiguous random variables



Law of large numbers for ambiguous random variables

