

人とロボットの共存・協働・協調における産業と社会応用 Human and robot coexistence, collaboration, and harmonization for industrial and serivice/social applications

2024/11/18 吹田 和嗣 Kazutsugu Suita







Human centered manufacturing in Safety2.0 activities



Productivity

with safety, health, and well-being



Collaboration **TOYOTA**

Share task space

Automation Coexistence

Safety1.0



Achieving both safety and productivity Reducing negative processes



RICH

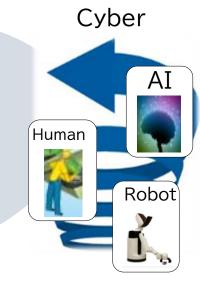
Real-time **Inter-Collaborative Harmoniz**ation with

Cyber-Physical technologies

Harmonization



Human-robot Sharing task learning results Improving each other deeply



Physical

Safety2.0

Safety1.0

Interaction level



Practical human robot collaboration for assembling





https://tsukuba.repo.nii.ac.jp/records/2000782

Achieving both productivity and safety with reducing burden work



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Safety1.0



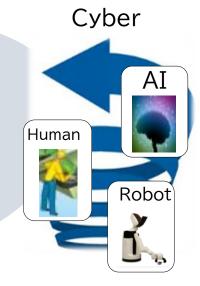
物理空間 **RICH**

Real-time **Inter-Collaborative Harmoniz**ation with

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Physical



Achieving both safety and productivity Reducing negative processes

Safety1.0

Safety2.0

Interaction level



Holistic approach to service robot application



Based on Safety2.0 Concept





Standards for robot

Safety requirements Management 対象分野 ロボット本体(機械)の安全 ロボット運用時の安全 業用ロボット ISO 10218/JIS B 8433 ISO 45001/労働安全衛生法

国内規格 (JIS Y 1001) のみ

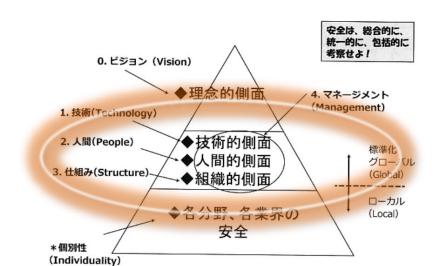
国際規格案を新規に提案

ISO 31101

industrial 産業用ロボット ISO 10218/JIS B 8433

Service サービスロボット ISO 13482/JIS B 8445
及び JIS B 8446-1~3

https://www.aist.go.jp/aist_j/news/pr20200902_2.html



Proposal from Japan



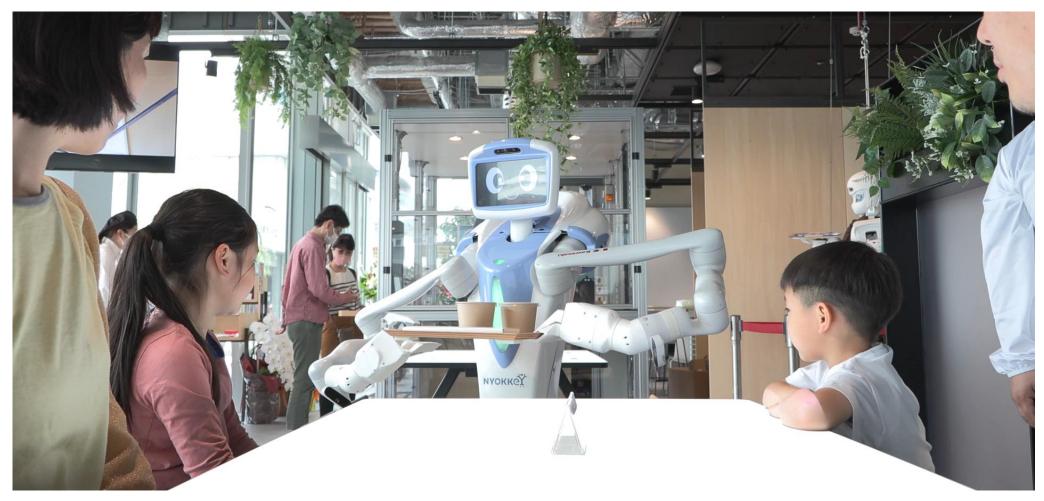
https://www.meti.go.jp/press/2023/1 1/20231113001/20231113001.html

Holistic approach
Importance of human, structure, and management factors



Practical restaurant service robot application





Future Lab. Haneda in Haneda innovation city Japan

https://answers.khi.co.jp/ja/connected-society/20220527j-01/

Various type robot system employment in service fields



Worker Engagement and Awareness - Hospitality



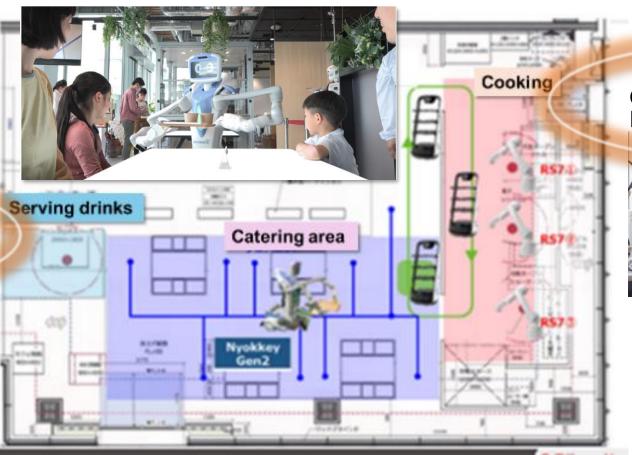


<Focused point>
Physical robot contact
with customers



Server: Nyokkey

up serving and down serving



<Focused point>
Cooking robot
Process situation



Cook: RS007L

Retort pouch
Warming
Cutting the pouch
Pouring into dishes

https://www.automaatioseura.fi/site/assets/files/4501/sias_2024_paper_29.pdf

Content of consideration differs from scene to scene, requiring "experience x attention" of the worker



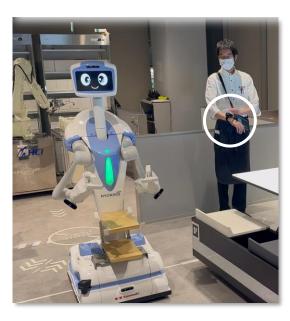
Safety2.0 application for enhancing resultant staff well-being



<Field voice> Robot can be easily stopped by anyone at any time, whenever they notice it.

For

Working restaurant staff's Job Satisfaction
 Improving customer satisfaction with hospitality





ANSHIN stop requirements

▽Pause without power shutdown

∇User-friendly design

- Wearable remote system
- Improving human interface

✓ Maintain robot motion trajectories

- Program stop function
- Easy to restart

https://www.automaatioseura.fi/site/assets/files/4501/sias_2024_paper_29.pdf

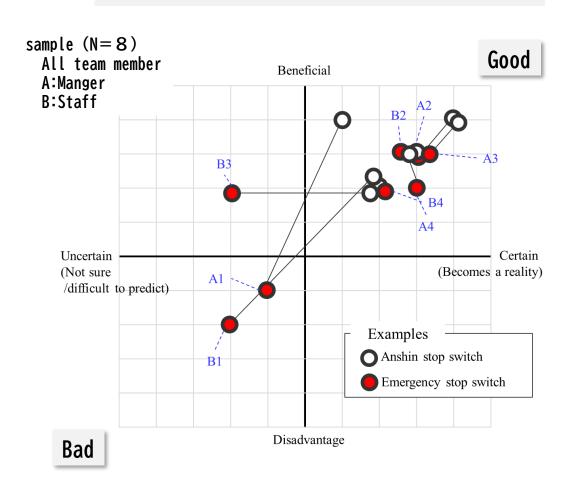
Developed ANSHIN stop install in actual operation of the restaurant



Human-robot harmonization and communication technology and its effects



Applied human behavior analysis



ANHISN stop evaluation results

- **▽Plotted in quadrant 1**High trend regardless of job title and experience
- **▽Same person comparison ANSHIN stop certainty and benefit can be improved.**
- ∀ Two veterans (A4 and B4 subjects)
 Knows when to press each stop switch
 Experience and skill
 - →Use both switch differently in different situations

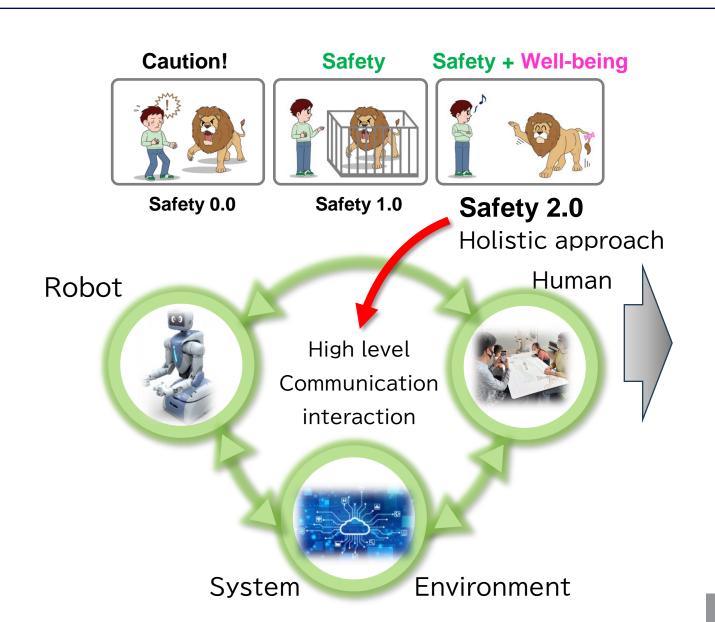
https://www.automaatioseura.fi/site/assets/files/4501/sias_2024_paper_29.pdf

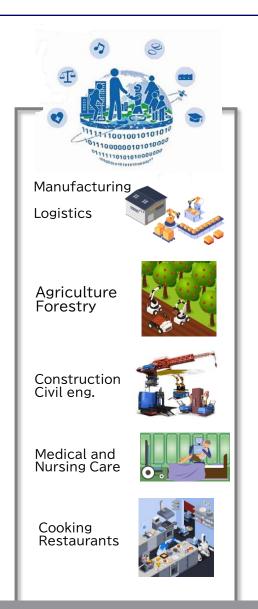
Effectiveness of "ANSHIN stop" in Human Applied Behavior Model



Establishing society every person can realize happiness (well-being)







https://www8.cao.go.jp/cstp/society5_0/society5_0.pdf

Solutions to Social Issues

Thank you for your attention!



